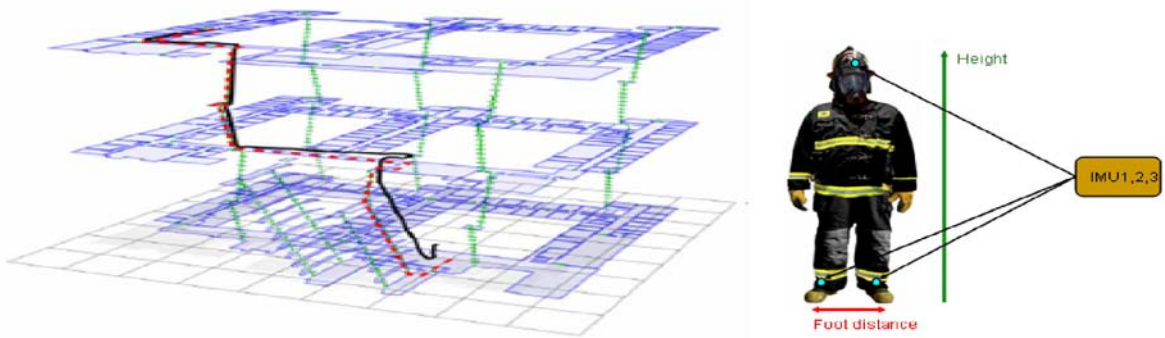
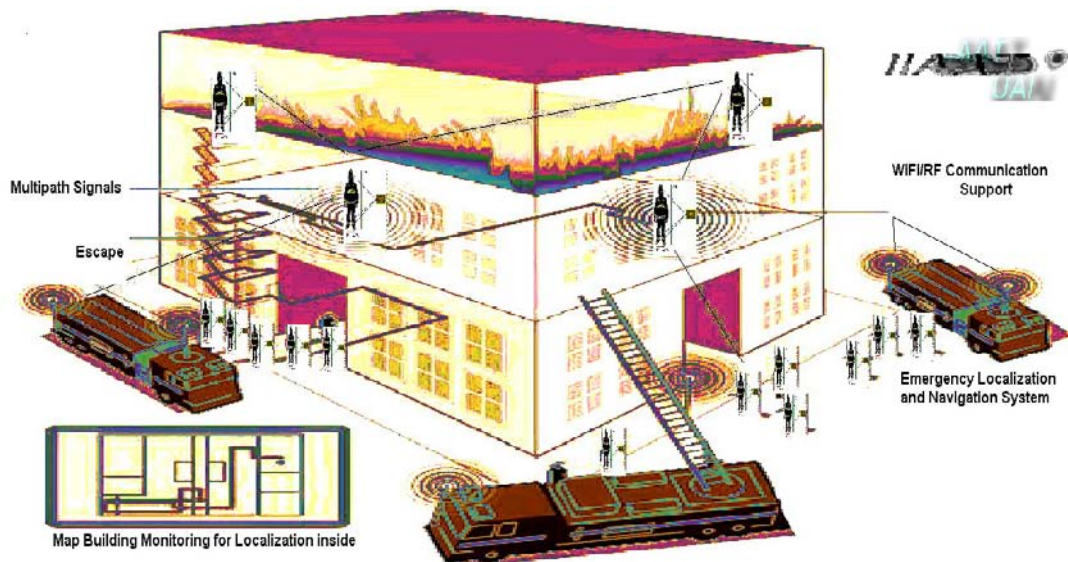


Project 8. Fire Fighters Indoor/Outdoor Localization and Navigation System

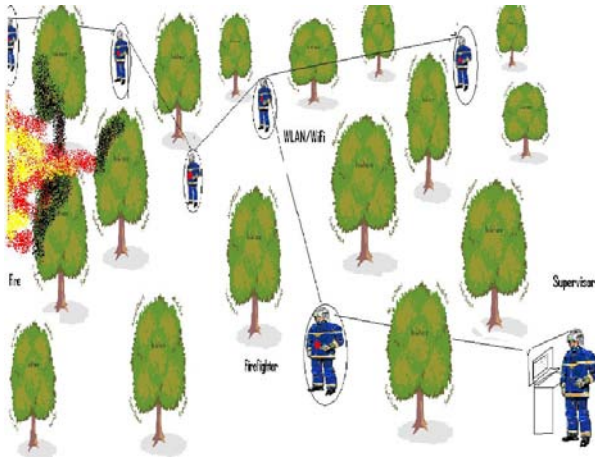
Both in outdoor and indoor application, the problem of fire Fighters localization and Navigation system in known and unknown environment is a very important for safety of them and the people whom have to be rescued .In our work we propose a solution to this problem using in outdoor ; GPS coupled with inertial sensors as accelerometers ,gyroscopes and compass using an adaptive filter able to estimate the navigation state as: position, velocity, heading...etc. for example in forest, when fireman are acting inside fire, this system with supervisor can aid them and constantly linked by communication system as WLAN and WiFi to permit the guidance. In indoor application, the problem is more complicated because the non working of GPS, we have to develop another solution and it is what we propose in our work, using only inertial sensors, compass and altimeter for navigation and RFID and/or WLAN/WiFi to communicate from inside the building to the outside sending position and direction of fireman who is as blind in fire, so the supervisor can guide him to save people who have to be rescued or guide him outside the building. This solution will permit to fireman to penetrate using optimum trajectory and fight fire as well as it is possible.



Indoor Localization and Navigation

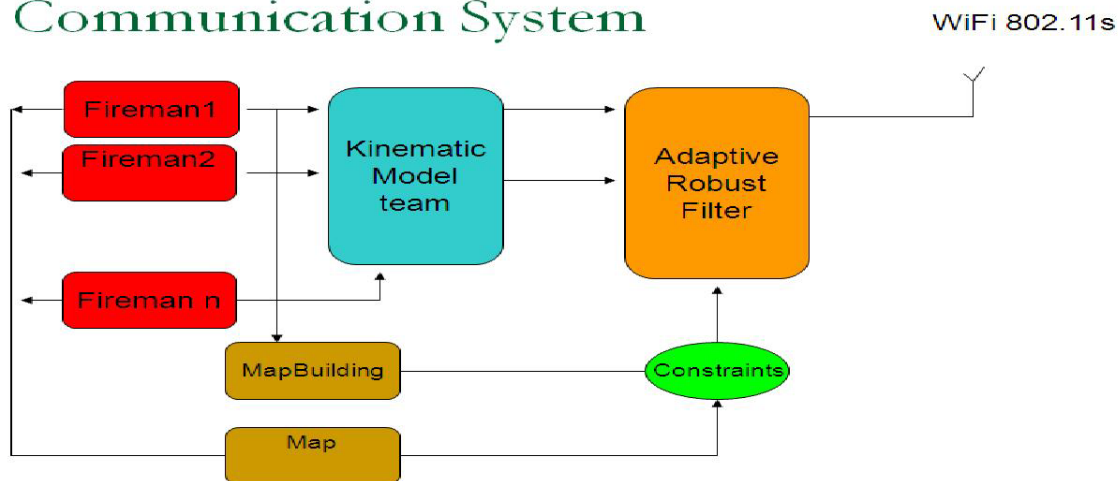


Outdoor (left) and indoor (right) Localization and guidance system



Outdoor Localization and guidance system

Inside/Outside Navigation and Communication System



References:

1. Benzerrouk.H, Nebylov.A, Yatsevitch. G, *Localization and Navigation System for Blinds Peoples in the City. Russian Patent N° 89221, issued on 08 November 2009, Moscow, Russia.*
2. Benzerrouk.H, Nebylov.A, Yatsevitch. G, *Intelligent Algorithms for Navigation on the surface of Mars Planet, IFAC ICONS, Istanbul Turkey, Special session2, "intelligent Control Systems in Aerospace"- 2009.*
3. Benzerrouk.H, Nebylov.A, Yatsevitch. G, *Original Solutions for Localization and Navigation on the surface of Mars Planet, IEEE Aerospace Conference ,Big Sky USA-2010.*
4. Benzerrouk.H, Nebylov.A, Yatsevitch. G, *Smart Algorithms for Localization and Navigation on the surface of Mars Planet, Based on Natural Constraints 18th IFAC Symposium on Automatic Control in Aerospace ACA'2010. 6 - 10 September 2010.*
5. Hamza Benzerrouk, Alexander Nebylov; "Original Integrated Navigation System GNSS/Compass for Localazation and Navigation of Blind peoples in the City", 17th International Conference on Integrated Navigation Systems, CSRI Elektropribor, Saint-Petersburg,Russia June 2010.
6. Hamza Benzerrouk, Alexander Nebylov; "Integrated Navigation System INS/GNSS Based on Joint Application of Robust Adaptive Linear and Nonlinear Filtering", 17th International Conference on Integrated Navigation Systems, CSRI Elektropribor, Saint-Petersburg,Russia June 2010.
7. Benzerrouk.H, Nebylov.A, Yatsevitch. G, "Indoor/Outdoor Firefighter's Localization and Navigation, European Navigation Conference on GNSS ", ENC GNSS 2010, Branchweig, Germany.